

Environnement et Changement climatique Canada







Objectives :

GMAC-2017

Extend the EC-EnKF to estimate CO₂ and CO and their fluxes for forecasting on weather timescales.

Since the winds are coupled to the tracer the forecast CO₂ spread includes uncertainty due to winds. This is an important advantage of coupled models over offline models in ensemble estimation/forecasting

Setup for modifications :

- GEM-MACH-GHG (Polavarapu et. al.) model with 0.9 degree resolution and 75 levels is used as the forward model.
- aircraft) is In-situ data (flask, tower and radiosonde assimilated with along observations.
- Ensemble size = 64
- Data are assimilated every 6 hours.

Modifications completed :

- meteorological The state been has augmented with CO_2 and the flux field.
- Variable localization (Kang et. al.) has been implemented in the EnKF. This ensures that the meteorological observations are not allowed to update CO_2 and the flux. Similarly the CO₂ observations are not allowed to impact the meteorogical variables.
- modifications tested by hese are assimilating radiosonde observations and only two surface flask CO₂ observations.

An ensemble based estimator is potentially better than flux inversion because the ensemble provides a state dependent estimate of covariance.

Work in progress :

- Include CO and flux field in the augmented state.
- 30°S Implement an Observation System Simulation Experiment (OSSE).
- The OSSE will use simulated radiosonde observations and simulated CO₂ and CO observations.
- The simulated observations will be at the same time and locations as the real flask, tower and aircraft observations.

The estimation of CO₂ fluxes with a coupled meteorology and tracer transport model

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carbon cycle data assimilation, JGR.





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